#### Maximum flow

#### Algorithms and Networks



## Today

- Maximum flow problem
- Variants
- Applications
- Briefly: Ford-Fulkerson; min cut max flow theorem
- Preflow push algorithm
- Lift to front algorithm



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#### The problem

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#### Problem

- Directed graph G=(V,E)
- Source  $s \in V$ , sink  $t \in V$ .

Variants in notation, e.g.: Write f(u,v) = -f(v,u)

- Capacity  $c(e) \in \mathbb{Z}^+$  for each *e*.
- Flow: function f:  $E \rightarrow N$  such that
  - For all e: f(e)  $\leq$  c(e)
  - For all v, except s and t: flow into v equals flow out of v
- Flow value: flow out of s
- Question: find flow from *s* to *t* with maximum value



### Maximum flow

Algoritmiek

- Ford-Fulkerson method
  - Possibly (not likely) exponential time
  - Edmonds-Karp version: O(*nm*<sup>2</sup>): augment over shortest path from *s* to *t*
- Max Flow Min Cut Theorem
- Improved algorithms: Preflow push; scaling
- Applications
- Variants of the maximum flow problem



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#### Variants: Multiple sources and sinks Lower bounds

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#### Variant

- Multiple sources, multiple sinks
- Possible maximum flow out of certain sources or into some sinks
- Models logistic questions



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#### Lower bounds on flow

Edges with *minimum* and maximum capacity

- For all  $e: l(e) \le f(e) \le c(e)$ 

$$\begin{array}{c} l(e) \\ c(e) \end{array}$$



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#### Flow with Lower Bounds

- Look for maximum flow with for each *e*:  $l(e) \le f(e) \le c(e)$
- Problem solved in two phases
  - First, find *admissible* flow
  - Then, augment it to a maximum flow
- Admissible flow: any flow *f*, with
  - Flow conservation
    - if  $v \notin \{s,t\}$ , flow into v equals flow out of v
  - Lower and upper capacity constraints fulfilled:
    - for each  $e: l(e) \le f(e) \le c(e)$



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A&N: Maximum flow

#### Transshipment

### Finding admissible flow 1

- First, we transform the question to: find an admissible *circulation*
- Finding admissible circulation is transformed to: finding maximum flow in network with new source and new sink
- Translated back



#### Circulations

- Given: digraph G, lower bounds *l*, upper capacity bounds *c*
- A circulation fulfills:
  - For all v: flow into v equals flow out of v
  - $-\mathbf{F}$ or all (u,v):  $l(u,v) \le f(u,v) \le c(u,v)$
- Existence of circulation: first step for finding admissible flow



#### Circulation vs. Flow

Model flow network with circulation network: add an arc (*t*,*s*) with large capacity (e.g., sum over all c(s, v) ), and ask for a circulation with f(t,s) as large as possible



f(t,s) = value(f)



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### Finding admissible flow

• Find admissible circulation in network with arc (*t*,*s*)

– Construction: see previous sheet

• Remove the arc (*t*,*s*) and we have an admissible flow



#### Finding admissible circulation

- Is transformed to: finding a maximum flow in a new network
  - New source
  - New sink
  - Each arc is replaced by three arcs



#### Finding admissible circulation



#### Finding admissible flow/circulation

- Find maximum flow from S' to T'
- If all edges from S' (and hence all edges to T') use full capacity, we have admissible flow:

 $-\mathbf{f}'(u,v) = \mathbf{f}(u,v) + l(u,v) \text{ for all } (u,v) \text{ in } \mathbf{G}$ 



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## From admissible flow to maximum flow

- Take admissible flow f (in original G)
- Compute a maximum flow f' from s to t in  $G_f$ 
  - Here  $c_f(u,v) = c(u,v) f(u,v)$
  - And  $c_f(v, u) = f(u, v) l(u, v)$ 
    - If (u, v) and (v, u) both exist in G: add ... (details omitted)
- f + f' is a maximum flow from s to t that fulfills upper and lower capacity constraints
- Any flow algorithm can be used



## Recap: Maximum flow with Lower bounds

- Find admissible flow f in G:
  - Add the edge (t,s) and obtain G'
    - Find admissible circulation in G':
      - Add new supersource s' and supersink t'
      - Obtain G'' by changing each edge as shown three slides ago
      - Compute with any flow algorithm a maximum flow in G"
      - Translate back to admissible circulation in G'
  - Translate back to admissible flow in G by ignoring (t,s)
- Comput G<sub>f</sub>
- Compute a maximum flow f' in G' with any flow algorithm
- Output <mark>f+f</mark>



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#### Applications



## Applications

- Logistics (transportation of goods)
- Matching

. . .

• Matrix rounding problem



### Matrix rounding problem

- p \* q matrix of real numbers  $D = \{d_{ij}\}$ , with row sums  $a_i$  and column sums  $b_i$ .
- Consistent rounding: round every d<sub>ij</sub> up or down to integer, such that every row sum and column sum equals rounded sum of original matrix
- Can be modeled as flow problem with lower and upper bounds on flow through edges



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## Reminder: Ford-Fulkerson and the min-cut max flow theorem



#### Ford-Fulkerson

- Residual network  $G_f$
- Start with 0 flow
- Repeat
  - Compute residual network
  - Find path P from *s* to *t* in residual network
  - Augment flow across P
  - Until no such path P exists



#### Max flow min cut theorem

- *s*-*t*-cut: partition vertices in sets S, T such that *s* in S, *t* in T. Look to edges (*v*, *w*) with *v* in S, *w* in T.
- Capacity of cut: sum of capacities of edges from S to T
- Flow across cut
- **Theorem**: minimum capacity of *s*-*t*-cut equals maximum flow from *s* to *t*.



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#### The preflow push algorithm



## Preflow push

- Simple implementation:  $O(n^2m)$
- Better implementation:  $O(n^3)$
- Algorithm maintains *preflow*: some flow out of *s* which doesn't reach *t*
- Vertices have *height*
- Flow is pushed to lower vertex
- Vertices sometimes are *lifted*



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#### Preflow

Notation from Introduction to Algorithms

- Function f:  $V * V \rightarrow \mathbf{R}$ 
  - Skew symmetry: f(u,v) = -f(v,u)
  - Capacity constraints:  $f(u,v) \le c(u,v)$
  - Notation: f(V,u)
  - For all *u*, except s:  $f(V,u) \ge 0$  (*excess flow*)
  - -u is *overflowing* when f(V,u) > 0.
  - Maintain: e(u) = f(V,u).



#### Height function

- h:  $V \rightarrow N$ :
  - -h(s)=n
  - -h(t)=0
  - For all  $(u,v) \in E_f$  (residual network): h(u) ≤ h(v)+1



#### Initialize

• Set height function h -h(s) = nDo not change -h(t) = 0-h(v) = 0 for all v except s • for each edge (s, u) do -f(s,u) = c(s,u); f(u,s) = -c(s,u)Initial preflow -e[u] = c(s,u);



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### Basic operation 1: Push

- Suppose e(u) > 0,  $c_f(u,v) > 0$ , and h[u] = h[v] + 1
- Push as much flow across (u,v) as possible  $\mathbf{r} = \min \{e[u], c_f(u,v)\}$   $f(u,v) = f(u,v) + \mathbf{r};$  f(v,u) = -f(u,v);  $e[u] = e[u] - \mathbf{r};$  $e[v] = e[v] + \mathbf{r}.$



#### Basic operation 2: Lift

- When no push can be done from overflowing vertex (except s,t)
- Suppose e[u] > 0, and for all  $(u, v) \in E_f : h[u] \le h[v], u \neq s, u \neq t$
- Set  $h[u] = 1 + \min \{h[v] | (u,v) \in E_f\}$



### Preflow push algorithm

- Initialize
- while push or lift operation possible do
  - Select an applicable push or lift operation and perform it

To do: correctness proof and time analysis



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#### Lemmas / Invariants

- If there is an overflowing vertex (except *t*), then a lift or push operation is possible
- The height of a vertex never decreases
- When a lift operation is done, the height increases by at least one.
- *h* remains a height function during the algorithm



## Another invariant and the correctness

- There is no path in  $G_f$  from s to t
  - Proof: the height drops by at most one across
    each of the at most *n*-1 edges of such a path
- When the algorithm terminates, the preflow is a maximum flow from *s* to *t* 
  - -f is a flow, as no vertex except *t* has excess
  - As  $G_f$  has no path from *s* to *t*, *f* is a maximum flow



#### Time analysis 1: Lemma

- If *u* overflows then there is a simple path from *u* to *s* in  $G_f$
- Intuition: flow must arrive from *s* to *u*: reverse of such flow gives the path
- Formal proof skipped



#### Number of lifts

- For all u: h[u] < 2n
  - h[s] remains *n*. When vertex is lifted, it has excess, hence path to *s*, with at most n - 1edges, each allowing a step in height of at most one up.
- Each vertex is lifted less than 2*n* times
- Number of lift operations is less than  $2n^2$



## Counting pushes

- Saturating pushes and not saturating pushes
  - Saturating: sends  $c_f(u,v)$  across (u,v)
  - Non-saturating: sends  $e[u] < c_f(u,v)$
- Number of saturating pushes
  - After saturating push across (u,v), edge (u,v) disappears from  $G_f$ .
  - Before next push across (u,v), it must be created by push across (v,u)
  - Push across (*v*,*u*) means that a lift of *v* must happen
  - At most 2n lifts per vertex: O(n) sat. pushes across edge
  - O(nm) saturating pushes



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#### Non-saturating pushes

• Look at 
$$\Phi = \sum_{v \in V} h[v]$$

- Initially  $\Phi = 0$ . e(v) > 0
- $\Phi$  increases by lifts in total at most  $2n^2$
- $\Phi$  increases by saturating pushes at most by 2n per push, in total  $O(n^2m)$
- Φ decreases at least one by a non-saturating push across (u,v)
  - After push, *u* does not overflow
  - v may overflow after push
  - -h(u) > h(v)
- At most  $O(n^2m)$  pushes



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### Algorithm

- Implement
  - -O(n) per lift operation
  - O(1) per push
- $O(n^2m)$  time



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#### Preflow-push fastened: The lift-to-front algorithm



#### Lift-to-front algorithm

- Variant of preflow push using  $O(n^3)$  time
- Vertices are discharged:
  - Push from edges while possible
  - If still excess flow, lift, and repeat until no excess flow
- Order in which vertices are discharge:
  - <mark>– lis</mark>t,
  - discharged vertex placed at top of list
  - Go from left to right through list, until end, then start anew



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#### Definition and Lemma

- Edge (*u*,*v*) is *admissible* 
  - $c_f(u,v) > 0$ , i.e.,  $(u,v) \in E_f$
  - h(u) = h(v) + 1
- The network formed by the admissible edges is **acyclic**.
  - If there is a cycle, we get a contradiction by looking at the heights
- If (u,v) is admissible and e[u] > 0, we can do a push across it. Such a push does not create an admissible edge, but (u,v) can become not admissible.



## Discharge procedure

- Vertices have adjacency list N[*u*]. Pointer *current*[*u*] gives spot in adjacency list.
- **D**ischarge(u)
  - -While e[*u*] > 0 do

 $\mathbf{v} = current[u];$ 

if v = NIL then {Lift(*u*); current[*u*] = head(N[*u*]);} elseif  $c_f(u,v) > 0$  and h[u] = h[v]+1 then Push(u,v); else current[*u*] = next-neighbor[*v*];



#### Discharge indeed discharges

- If *u* is overflowing, then we can do either a lift to *u*, or a push out of *u*
- Pushes and Lifts are done when Preflow push algorithm conditions are met.



#### Lift-to-front algorithm

- Maintain linked list L of all vertices except s, t.
- Lift-to-front(G,*s*,*t*)
  - Initialize preflow and L
  - **for** all v **do** current[v] = head[N(v)];
  - -u is head of L
  - while *u* not NIL do
    - oldheight = h[u];
    - Discharge(u);
    - **if** h[u] > oldheight**then**move*u*to front of list L
    - u = next[u];



#### Remarks

- Note how we go through L.
- Often we start again at almost the start of L...
- We end when the entire list is done.
- For correctness: why do we know that no vertex has excess when we are at the end of L?



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## A definition: Topological sort

- A directed acyclic graph is a directed graph without cycles. It has a *topological sort*:
  - An ordering of the vertices  $\tau: V \rightarrow \{1, 2, ..., n\}$  (bijective function), such that for all edges  $(v,w) \in E: \tau(v) < \tau(w)$



L is a topological sort of the network of admissible edges

- If (*u*,*v*) is an admissible edge, then *u* is before *v* in the list L.
  - Initially true: no admissible edges
  - A push does not create admissible edges
  - -A fter a lift of *u*, we place *u* at the start of L
    - Edges (*u*,*v*) will be properly ordered
    - Edges (*v*,*u*) will be destroyed



# Lift-to-front algorithm correctly computes a flow

- The algorithm maintains a preflow.
- Invariant of the algorithm: all vertices before the vertex *u* in consideration have no excess flow.
  - Initially true.
  - Remains true when *u* is put at start of *L*.
  - Any push pushes flow towards the end of L.
    - L is topological sort of network of admissible edges.
- When algorithm terminates, no vertex in L has excess flow.



## Time analysis - I

- $O(n^2)$  lift operations. (As in preflow push.)
- O(*nm*) saturating pushes.
- Phase of algorithm: steps between two times that a vertex is placed at start of *L*, (and before first such and last such event.)
- $O(n^2)$  phases; each handling O(n) vertices.
- All work except discharges:  $O(n^3)$ .



## Time of discharging

- Lifts in discharging: O(n) each,
   O(n<sup>3</sup>) total
- Going to next vertex in adjacency list
  - O(degree(u)) work between two lifts of u
  - O(*nm*) in total
- Saturating pushes: O(*nm*)
- Non-saturating pushes: only once per discharge, so  $O(n^3)$  in total.



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A&N: Maximum flow

Conclusion: O(n<sup>3</sup>) time for the Lift to front algorithm

#### Conclusions

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### Many other flow algorithms

- Push-relabel (variant of preflow push)
   O(*nm* log (*n*<sup>2</sup>/*m*))
- Scaling (exercise)



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#### A useful theorem

- Let *f* be a circulation. Then *f* is a nonnegative linear combination of cycles in G.
  - Proof. Ignore lower bounds. Find a cycle c, with minimum flow on c r, and use induction with f r \* c.
- If *f* is integer, `*integer scalared*' linear combination.
- Corollary: a flow is the linear combination of cycles and paths from *s* to *t*.
  - Look at the circulation by adding an edge from t to s and giving it flow value(f).



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#### Next

#### • Minimum cost flow



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