A Lightweight Implementation of Generics and Dynamics

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Abstract

The recent years have seen a number of proposals for extending statically typed languages by dynamics or generics. Most proposals — if not all — require significant extensions to the underlying language. In this paper we show that this need not be the case. We propose a particularly lightweight extension that supports both dynamics and generics. Furthermore, the two features are smoothly integrated: dynamic values, for instance, can be passed to generic functions. Our proposal makes do with a standard Hindley-Milner type system augmented by existential types. Building upon these ideas we have implemented a small library that is readily usable both with Hugs and with the Glasgow Haskell compiler.

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1 Introduction

A desirable feature of programming languages is *safety*. Broadly speaking, safe programming languages prevent untrapped errors at run time [25]. Safety can be achieved either by static checking, by dynamic checking, or by a combination of static and dynamic checks. Each approach has its pros and cons.

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Dynamically typed languages, like Scheme and Java, preserve type information until run time, enabling concise definitions of utility functions (such as *show*, '==', *compare*) using dynamic casts, generic functions, or multimethods. However, type preservation introduces space and run-time overhead that is left for the compiler to optimize away. Also, with dynamic typing, many type errors that could be caught at compile time are not detected until run time.

Statically typed languages, like Haskell and ML, are at the other extreme. Typechecking occurs at compile time and type information is discarded after compilation, so it is impossible to write functions whose behaviour depends on run-time type information. As a result, utility and communication functions cannot be defined once and for all. Instead, programmers must provide new versions of them for each new data type. Their definitions are essentially determined by type structure, but must be written out explicitly because this regular behaviour cannot be expressed using the Hindley-Milner type system.

Previous approaches to supporting generic programming, typedependent optimizations, and dynamic casts within statically typed languages include:

- explicit dynamic typing [21, 1], in which the language is augmented with a *Dynamic* type and a *typecase* or *cast* construct;
- polytypic programming [19, 5, 16], in which type-dependent functions written in a language extension are translated to pure polymorphic functions;
- ad-hoc polymorphism [31, 11] (i.e. Haskell's type classes), in which types are associated with classes that indicate the presence of overloaded functions like '==';
- intensional polymorphism [14], in which type information is preserved throughout compilation, so that run-time type dispatch can be performed.

However, none of the above techniques is both easy to implement and powerful enough to support dynamics and generics. Explicit dynamic typing is nontrivial to implement and to prove type-safe, especially in the presence of polymorphism. Polytypic programming is typically implemented using source-to-source translation, and does not address dynamic typing. Type classes have long been present in Haskell, but are limited in expressiveness. The original type-passing implementation of intensional polymorphism changes the language's semantics and violates the parametricity theorem, precluding a simple type-erasing language implementation and complicating soundness proofs. Also, it is not clear how or whether dynamic typing and generic programming features can be safely combined; to date, each has been studied in isolation.

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Recent work has addressed some of these shortcomings: Leroy and Mauny [21] and Abadi et al. [1] showed how to safely combine dynamics and polymorphism. Hinze and Peyton Jones [18] have introduced derivable type classes, which permit polytypic definitions of type classes. Crary, Weirich, and Morrisett [9] have reconciled intensional polymorphism with type erasure using explicit type representations. However, implementations of dynamics, derivable type classes, and type representations still seem to require substantial compiler modifications and soundness proofs.

In this paper, we show that this need not be the case. We present an encoding of type representations in Haskell 98 [23] augmented with existential types, and show how to use type representations to define simple polytypic functions, type Dynamic, and finally generic functions of the same flavour as those definable by derivable type classes. This provides a simple and safe implementation for generics and dynamics in Haskell, with no additional compiler support or proofs of type soundness required. It also sheds light on the relationship between generics and dynamics and shows that they can coexist and interact peacefully.

The rest of the paper is structured as follows. Sec. 2 explains how to define type representations in Haskell and illustrates their use in programming functions that work for a family of types. Type representations are also at the heart of dynamics in Sec. 3. Sec. 4 shows how to achieve true genericity, the ability to define functions that work for all types. Finally, Sec. 5 reviews related work and Sec. 6 concludes. For reference, the complete implementation of the Haskell library is included in App. A.

Programming with type representations 2

Let's start modest. Assume that you have a possibly infinite family of types and you want to define a function, say, equality, that works for all types of this family (we call such a function polytypic). For concreteness, let us consider the family of types given by the following grammar.

$$\tau$$
 ::= Int | 1 | $\tau + \tau$ | $\tau \times \tau$

We assume that the unit type, the sum type and the pair type are given by the following declarations (Haskell already offers isomorphic types but we introduce new types for reasons to become clear later).

$$\begin{aligned} & \text{data } 1 &= Unit \\ & \text{data } \alpha + \beta &= Inl \ \alpha \ | Inr \ \beta \\ & \text{data } \alpha \times \beta &= \alpha : \times : \beta \end{aligned}$$

Now, in Haskell one would immediately fall back on the class system to implement such a type-indexed family of functions. The equality function is assigned the type¹

$$=: \quad \forall \alpha . (Eq \alpha) \Rightarrow \alpha \to \alpha \to Bool.$$

The so-called class context '(Eq α) \Rightarrow ' makes explicit that the equality function does not work for all types but only for those types that are instances of the type class Eq.

The purpose of this section is to show that one can also do without type classes. The basic idea is to pass '==' an additional argument that represents the type at which the equality function is called. As a first try we could assign '==' the type $\forall \alpha . Rep \rightarrow \alpha \rightarrow \alpha \rightarrow Bool$,

where *Rep* is the type of type representations. A moment's reflection, however, reveals that this won't work. The parametricity theorem [29] implies that a function of this type must necessarily ignore its second and its third argument. The trick is to use a parametric type for type representations:

$$(==) \quad :: \quad \forall \alpha \, . \, Rep \, \alpha \to \alpha \to \alpha \to Bool.$$

Here *Rep* τ is the type representation of τ . The one-million-dollar question is, of course, how can we define such a type? There are at least two possibilities, both of which require extensions to Haskell's data construct.

2.1 Alternative 1: polymorphic data signatures

We inhabit Rep τ by defining for each type constructor a corresponding value constructor that represents the type. For the above family of types we introduce

$$\begin{array}{lll} R_{Int} & :: & Rep \ Int \\ R_1 & :: & Rep \ 1 \\ R_+ & :: & \forall \alpha . Rep \ \alpha \to (\forall \beta . Rep \ \beta \to Rep \ (\alpha + \beta)) \\ R_{\times} & :: & \forall \alpha . Rep \ \alpha \to (\forall \beta . Rep \ \beta \to Rep \ (\alpha \times \beta)). \end{array}$$

For instance, the type $1 + (Int \times Int)$ is represented by the value $R_+ R_1 (R_{\times} R_{Int} R_{Int})$ of type $Rep (1 + (Int \times Int))$.

Of course, the declarations above are not valid Haskell since data constructors can only be introduced via data declarations. But, let's accept this for the moment.

Given these prerequisites we can easily define a polytypic equality function that works for all representable types. We simply pattern match on the 'type' argument.

$$\begin{array}{rcl} rEqual & :: & \forall \tau . Rep \ \tau \to \tau \to \tau \to Bool \\ rEqual \ (R_{Int}) \ t_1 \ t_2 &= t_1 = t_2 \\ rEqual \ (R_1) \ t_1 \ t_2 &= \mathbf{case} \ (t_1, t_2) \ \mathbf{of} \\ & (Unit, Unit) \to True \\ rEqual \ (R_+ \ r_{\alpha} \ r_{\beta}) \ t_1 \ t_2 \\ &= \mathbf{case} \ (t_1, t_2) \ \mathbf{of} \\ & (Inl \ a_1, Inl \ a_2) \to rEqual \ r_{\alpha} \ a_1 \ a_2 \\ & (Inr \ b_1, Inr \ b_2) \to rEqual \ r_{\beta} \ b_1 \ b_2 \\ & - \to False \\ rEqual \ (R_{\times} \ r_{\alpha} \ r_{\beta}) \ t_1 \ t_2 \\ &= \mathbf{case} \ (t_1, t_2) \ \mathbf{of} \\ & (a_1 ::: b_1, a_2 ::: b_2) \to \\ & rEqual \ r_{\beta} \ b_1 \ b_2 \\ & - Fequal \ r_{\alpha} \ a_1 \ a_2 \land rEqual \ r_{\beta} \ b_1 \ b_2 \end{array}$$

Note that each equation defines a function whose type is a true instance of the declared type: rEqual (R_{Int}), for instance, has type Int \rightarrow Int \rightarrow Bool.

A polytypic function can also be defined in terms of other polytypic functions. The function *rElem*, for instance, implements polytypic list membership.

$$\begin{array}{ll} rElem & :: & \forall \tau. Rep \ \tau \to \tau \to [\tau] \to Bool \\ rElem \ r_{\tau} \ t \ x & = & or \ [rEqual \ r_{\tau} \ t \ a \mid a \leftarrow x] \end{array}$$

REMARK 1. The function rElem hints at one essential difference to Haskell's class system. Consider the class-based variant of rElem:

elem ::
$$\forall \alpha . (Eq \alpha) \Rightarrow \alpha \rightarrow [\alpha] \rightarrow Bool$$

The class context records precisely on which overloaded function elem depends. For instance, if elem additionally called show at type

F1

¹We will always write universal quantifiers explicitly.

 α , then Show α would be added to the class context. By contrast, the signature of the type-passing implementation would not change if it called a type-passing rShow. \Box

We have already noted that in Haskell data constructors can only be introduced by **data** declarations. Unfortunately, we cannot define *Rep* α via a **data** declaration since none of the data constructors has result type *Rep* α . We require a slight extension that allows us to instantiate the declared type to some specific instance.

data Rep τ = R_{Int} with $\tau = Int$ | R_1 with $\tau = 1$ | $\forall \alpha \beta . R_+ (Rep \alpha) (Rep \beta)$ with $\tau = \alpha + \beta$ | $\forall \alpha \beta . R_{\times} (Rep \alpha) (Rep \beta)$ with $\tau = \alpha \times \beta$

The idea is to assign R_{Int} the type $Rep \tau$ with the additional constraint that $\tau = Int$, recorded by the **with** clause. As an aside, note that a universal quantifier in front of a constructor name acts as an *existential quantifier*. So $R_+ r_{\alpha} r_{\beta}$ has type $Rep \tau$ for *some* types α and β with $\tau = \alpha + \beta$. Existential types are supported both by Hugs and by the Glasgow Haskell compiler.

REMARK 2. Equational type constraints have been studied in the context of module systems for ML [20, 13] and typed closure conversion in the presence of intensional polymorphism [22]. In those contexts, the problem is that important relationships between types are hidden by modular abstraction or existential quantification; it is solved using translucent sum types, singleton kinds, or restricted type equations in order to make enough type sharing information evident in the module or closure type.

Unfortunately, this prior work is not directly applicable, since it addresses type sharing between elements of a module or existential package, not type equations that depend on data type cases. For example, singleton kinds would not help because each case of Rep would require τ to have a different singleton kind. Perhaps this could be addressed using kind polymorphism, but this complicates the type system even further.

Fortunately, we don't have to wait for yet another extension to Haskell's already quite impressive type system since **with** clauses can be simulated in Haskell 98 using embedding-projection pairs or *equvalence types*.

2.2 Alternative 2: equivalence types

In a type system corresponding to a consistent logical system, we could (motivated by the Curry-Howard isomorphism) think of **with** $\alpha = \beta$ clauses as propositions asserting that α and β are equivalent in some sense. This notion of equivalence could range from strict type equality to logical equivalence (that is, equivalence of type inhabitation). Propositional equivalence is typically defined as "if and only if": $A \equiv B$ means $(A \Rightarrow B) \land (B \Rightarrow A)$. Recall that conjunctions correspond to product types and implications to function types. Thus, we could define an *equivalence type* $\tau \leftrightarrow \tau'$ corresponding to the proposition that the types τ and τ' are equivalent as $(\tau \rightarrow \tau') \times (\tau' \rightarrow \tau)$. The function components can be thought of as casts from τ to τ' and back. In Haskell we declare

data $\alpha \leftrightarrow \beta = EP\{from :: \alpha \rightarrow \beta, to :: \beta \rightarrow \alpha\}.$

An element ep of type $\tau \leftrightarrow \tau'$ is a "proof" that the two types are equivalent.^2

Turning to the definition of *Rep* we replace each type constraint with $\tau = \tau'$ by the corresponding equivalence type $\tau \leftrightarrow \tau'$.

Additionally, we introduce so-called *smart constructors* corresponding to the R_{τ} constructors of the previous section that incorporate the reflexive equivalence value *self* as a proof of equivalence.

It remains to adapt the polytypic equality function to the new definition of *Rep*. The changes are straightforward: whenever we analyze a value *e* of type τ equivalent to τ' , we replace *e* by *from ep e* where *ep*:: $\tau \leftrightarrow \tau'$ is the corresponding proof of equivalence.

$rEqual \qquad :: rEqual (R_{Int} ep) t_1 t_2 =$	$\forall \tau . Rep \ \tau \rightarrow \tau \rightarrow \tau \rightarrow Bool$ from ep t ₁ == from ep t ₂
$rEqual (R_1 ep) t_1 t_2 = rEqual (R_1 ep) t_1 t_2 =$	
$IEqual (K_1 ep) i_1 i_2 =$	$(Unit, Unit) \rightarrow True$
<i>rEqual</i> $(R_+ r_{\alpha} r_{\beta} ep) t_1 t_2$	
=	case (from $ep t_1$, from $ep t_2$) of
	$(Inl a_1, Inl a_2) \rightarrow rEqual r_{\alpha} a_1 a_2$ $(Inr b_1, Inr b_2) \rightarrow rEqual r_{\beta} b_1 b_2$
	$- \rightarrow False$
<i>rEqual</i> ($R_{\times} r_{\alpha} r_{\beta} ep$) $t_1 t_2$	
=	case (from $ep t_1$, from $ep t_2$) of
	$(a_1:::b_1,a_2:::b_2) \rightarrow$
	<i>rEqual</i> $r_{\alpha} a_1 a_2 \wedge rEqual r_{\beta} b_1 b_2$

It is important to note that *rEqual* is polymorphically recursive: the recursive calls are at the existentially quantified types α and β . This means that the type signature is mandatory, otherwise the code would not typecheck.

The equality function takes values of the 'generic' type τ apart. When we *construct* a value of type $\tau = \tau'$, then we must wrap *to ep* around the constructed value. The polytypic function *rMinBound*, which constructs the least value of a type, serves as an example.

rMinBound	::	$\forall \tau . Rep \ \tau \rightarrow \tau$
$rMinBound (R_{Int} ep)$	=	to ep (minBound)
rMinBound $(R_1 ep)$	=	to ep (Unit)
<i>rMinBound</i> $(R_+ r_{\alpha} r_{\beta} ep)$	=	to ep (Inl (rMinBound r_{α}))
<i>rMinBound</i> $(R_{\times} r_{\alpha} r_{\beta} ep)$	=	to ep (rMinBound r_{α}
I.		:×: <i>rMinBound</i> r_{β})

phism and use of the terms "proposition" and "proof" for equivalence types and values is not formally justified. In Haskell, an equivalence pair only guarantees that α can be cast to β and vice versa, with nontermination a possibility for either case. This turns out to be enough for our purposes, since it still lets us encode representations safely. In practice, all casts witnessing equivalences are expected to terminate; usually, they are the identity.

²Haskell is not strongly normalizing and does not correspond to a consistent logic, so our appeal to the Curry-Howard isomor-

The polytypic function *rMemo*, which memoizes a given function, is an intriguing example of a function that both analyzes and synthesizes values of the generic type.

$$\begin{array}{rll} rMemo & :: & \forall \tau \vee .Rep \ \tau \to (\tau \to \nu) \to (\tau \to \nu) \\ rMemo \ (R_{Int} \ ep) \ f & = & \lambda t \to f \ t & -- \ no \ memoization \\ rMemo \ (R_1 \ ep) \ f & = & \lambda t \to \mathbf{case} \ from \ ep \ t \ \mathbf{of} \\ Unit \to fUnit \\ \mathbf{where} \ fUnit & = & f \ (to \ ep \ (Unit)) \\ rMemo \ (R_+ \ r_\alpha \ r_\beta \ ep) \ f & = & \lambda t \to \mathbf{case} \ from \ ep \ t \ \mathbf{of} \\ Inl \ a \to fInl \ a \\ Inr \ b \to fInr \ b \\ \mathbf{where} \ fInl & = & rMemo \ r_\alpha \ (\lambda a \to f \ (to \ ep \ (Inl \ a))) \\ fInr & = & rMemo \ r_\beta \ (\lambda b \to f \ (to \ ep \ (a \ x \ case)))) \\ rMemo \ (R_\times \ r_\alpha \ r_\beta \ ep) \ f & = & \lambda t \to \mathbf{case} \ from \ ep \ t \ \mathbf{of} \\ a \ :: \ b \to fPair \ a \ b \\ \mathbf{where} \ fPair & = & rMemo \ r_\alpha \ (\lambda a \to f \ (to \ ep \ (a \ x \ case)))) \\ \end{array}$$

To see how *rMemo* works note that the helper definitions *fUnit*, *fInl*, *fInr*, and *fPair* do not depend on the actual argument of *f*. Thus, once *f* is given, they can be readily computed. Memoization relies critically on the fact that they are computed only on demand and then at most once. This is guaranteed if the implementation is *fully lazy*. The interested reader is referred to Hinze [15] for background information. ³

New types

So far equivalence types $\tau \leftrightarrow \tau'$ have actually consisted of proofs of type equality, since they have been instantiated only with identity functions. But we could also interpret an element of $\tau \leftrightarrow \tau'$ as a proof that the two types are *isomorphic* rather than equal. Coincidentally, Haskell offers a linguistic construct for introducing a new type that is isomorphic to an existing type. Consider as an example the type of triples.

newtype
$$Tri \alpha \beta \gamma = To_{Tri} \{ from_{Tri} :: \alpha \times (\beta \times \gamma) \}$$

The declaration defines $Tri \alpha \beta \gamma$ to be isomorphic to $\alpha \times (\beta \times \gamma)$ with the functions To_{Tri} and $from_{Tri}$ witnessing the isomorphism. Since $Tri \alpha \beta \gamma$ is isomorphic to an existing type, we can represent it as follows.

$$\begin{array}{rcl} r_{Tri} & :: & \forall \alpha. Rep \ \alpha \to (\forall \beta. Rep \ \beta \to (\forall \gamma. Rep \ \gamma \to Rep \ (Tri \ \alpha \ \beta \ \gamma))) \\ r_{Tri} \ r_{\alpha} \ r_{\beta} \ r_{\gamma} & = & R_{\times} \ r_{\alpha} \ (r_{\times} \ r_{\beta} \ r_{\gamma}) \ (EP \ from_{Tri} \ To_{Tri}) \end{array}$$

Now, if we pass a triple to a polytypic function, then the isomorphisms *from*_{Tri} and *To*_{Tri} are automatically called at the appropriate places. Furthermore, since *Tri* α $\beta \gamma$ is *implemented* by the type on the right-hand side, both casts amount to the identity function at run time. This also means that a new type and its implementation type are treated alike, which may or may not be what you want. Indeed, equivalence types need not contain actual isomorphism pairs;

for example we can assert the equivalence of *Int* and [*Float*] with $\lambda x \rightarrow []$ and $\lambda l \rightarrow 0$. Ensuring that equivalence cast pairs are the identity or form an isomorphism is not expressible in Haskell, so these are external proof obligations.

Genuine type equality

We have seen in the previous section that the equivalence type $\tau \leftrightarrow \tau'$ does not guarantee that τ and τ' are actually equal (and we have used this to good effect). An intriguing question is whether we can devise an equivalence type that only admits equal types. Perhaps surprisingly, this is indeed possible and even more surprisingly, the underlying idea goes back to Leibniz—see Wadler [30] for a related application of Leibniz's idea. According to Leibniz, two terms are equal if one may be substituted for the other. Adapting this principle to types, we define,

newtype
$$\alpha \leftrightarrow \beta = EP\{unEP :: \forall \phi . \phi \alpha \rightarrow \phi \beta\}.$$

Note that the universally quantified type variable ϕ ranges over type constructors of kind $\star \rightarrow \star$. Thus, an element of $\alpha \leftrightarrow \beta$ is a function that converts an element of type $\phi \alpha$ into an element of $\phi \beta$ for *any* type constructor ϕ . We introduce a constant *self* expressing the reflexivity rule:

$$self :: \forall \alpha . \alpha \leftrightarrow \alpha$$
$$self = EP id$$

In a strongly normalizing type system like F_{ω} , the only inhabitant of $\alpha \leftrightarrow \alpha$ is the identity $\Lambda f.\lambda x.x$. If α and β are not equal, then the type $\alpha \leftrightarrow \beta$ is empty. In Haskell, there are additional inhabitants arising from nontermination. However, attempting to use such elements to cast between α and β will result in divergence.

To provide the same functionality as before we have to define functions that given a proof of type equality cast one type into the other. The *from* function is easy: we substitute the identity type for ϕ .

newtype
$$Id a = Id\{unId::\alpha\}$$

from :: $\forall \alpha \beta . (\alpha \leftrightarrow \beta) \rightarrow (\alpha \rightarrow \beta)$
from $ep = unId \cdot unEP ep \cdot Id$

The *to* function is more subtle: we first substitute the type constructor $\Psi x = x \rightarrow \alpha$ for ϕ . This gives us a function of type $(\alpha \rightarrow \alpha) \rightarrow (\beta \rightarrow \alpha)$, which we then apply to the identity function.

newtype
$$\alpha \leftarrow \beta = Inv\{unInv :: \beta \rightarrow \alpha\}$$

to $:: \forall \alpha \beta . (\alpha \leftrightarrow \beta) \rightarrow (\beta \rightarrow \alpha)$
to $ep = unInv (unEP ep (Inv id))$

Interestingly, both definitions of $\alpha \leftrightarrow \beta$ have precursors in the literature: they underly, for instance, Weirich's implementation of typesafe cast [32]. Though the above definition of $\alpha \leftrightarrow \beta$ is attractive, we will stick to the first variant as we rely on the broader interpretation of type equivalence as types being isomorphic.

A type class for type representations

When we call a polytypic function, we have to supply a type representation as an argument. Of course, if we are working in Haskell, we can use the class system for this purpose.

³In [15] memoization is defined as the composition of a function that constructs a memo table and a function that queries the table. If we fuse the two functions thereby eliminating the memo data structure, we obtain the *rMemo* function above. Thanks are due to Koen Claessen for bringing this to our attention. Despite appearance, the memo data structures did not vanish into thin air. Rather, they are now built into the closures. For instance, the memo table for a disjoint union is a pair of memo tables. The closure for *rMemo* ($R_+ r_{\alpha} r_{\beta} ep$) *f* consequently contains a pair of memoized functions, namely *flnl* and *flnr*.

We define type class Representable as follows:

class Representable
$$\tau$$
 where
rep :: Rep τ
instance Representable Int where
rep = r_{Int}
instance Representable 1 where
rep = r_1
instance (Representable α , Representable β) =
Representable ($\alpha + \beta$) where
rep = r_+ rep rep
instance (Representable α , Representable β) =
Representable ($\alpha \times \beta$) where
rep = r_{\sim} rep rep

Building upon the type class we can define a variant of polytypic equality that automatically constructs the type representation.

 $\begin{array}{lll} cEqual & :: & \forall \tau . (Representable \ \tau) \Rightarrow \tau \rightarrow \tau \rightarrow Bool \\ cEqual \ t_1 \ t_2 & = & rEqual \ rep \ t_1 \ t_2 \end{array}$

It is important to note, however, that this use of the class system is just a convenience, not a necessity for programming with representations.

3 Dynamics

3.1 The type Dynamic

A dynamic value is a pair consisting of the value itself and a representation of its type. As noted by [14, 9], we can readily define *Dynamic* using the type of type representations *Rep* as

data Dynamic	=	$\forall \alpha . Dyn \ (Rep \ \alpha) \ \alpha$
dynamic	::	$\forall \alpha. (Representable \ \alpha) \Rightarrow \alpha \rightarrow Dynamic$
dynamic a	=	Dyn rep a.

The existential quantifier (which is written as a universal quantifier) effectively hides the type of the dynamic value. It goes without saying that dynamic values thus defined are first-class citizens: we can, for instance, construct a list of dynamic values.

Now, what can we do with a value $Dyn r_{\alpha} a$ of type Dynamic? Not that much so far. If we have a polytypic function f of type $\forall \tau . Rep \tau \rightarrow \tau \rightarrow v$ where τ does not appear in v, then we can call $f r_{\alpha} a$. The polytypic function analyzes the type representation r_{α} and takes the appropriate action (the existentially quantified type variable cannot escape, since τ does not appear in v). However, we cannot take the equality of two dynamic values or cast a dynamic value into a static value of a given type. For both applications we have to check two type representations for equality, which is what we tackle next.

The function *unify* takes two type representations and possibly returns a proof of their equivalence.

unify ::
$$\forall \tau_1 \tau_2 . Rep \tau_1 \rightarrow Rep \tau_2 \rightarrow Maybe (\tau_1 \leftrightarrow \tau_2)$$

The run-time unification essentially combines proofs of equivalence. Assume, for instance, that *unify* is called with $R_{Int} ep_1 ::$ $Rep \tau_1$ and $R_{Int} ep_2 :: Rep \tau_2$. The proofs $ep_1 :: \tau_1 \leftrightarrow Int$ and $ep_2 :: \tau_2 \leftrightarrow Int$ can be combined into a proof of $\tau_1 \leftrightarrow \tau_2$ by applying the laws of symmetry and transitivity. These laws correspond to the functions *inv* and '\$', respectively.

$$\begin{array}{lll} inv & :: & \forall \alpha \ \beta. \ (\alpha \leftrightarrow \beta) \to (\beta \leftrightarrow \alpha) \\ inv f & = & EP\{from = to \ f, to = from f \ \} \\ (\diamond) & :: & \forall \alpha \ \beta \ \gamma. \ (\beta \leftrightarrow \gamma) \to (\alpha \leftrightarrow \beta) \to (\alpha \leftrightarrow \gamma) \\ f \diamond g & = & EP\{from = from \ f \cdot from \ g, to = to \ g \cdot to \ f \ \} \end{array}$$

The unification procedure is slightly more complicated for parametric types. Assume, for instance, that *unify* is passed the representations $R_+ r_{\alpha_1} r_{\beta_1} ep_1 :: Rep \tau_1$ and $R_+ r_{\alpha_2} r_{\beta_2} ep_2 :: Rep \tau_2$. The arguments provide proofs $ep_1 :: \tau_1 \leftrightarrow (\alpha_1 + \beta_1)$ and $ep_2 :: \tau_2 \leftrightarrow (\alpha_2 + \beta_2)$. Through recursive invocations of *unify* we possibly obtain proofs of $\alpha_1 \leftrightarrow \alpha_2$ and $\beta_1 \leftrightarrow \beta_2$. Using the law of congruence we can then construct a proof of $(\alpha_1 + \beta_1) \leftrightarrow (\alpha_2 + \beta_2)$. Finally, the subproofs are combined into a proof of $\tau_1 \leftrightarrow \tau_2$ by applying symmetry and transitivity. The law of congruence corresponds to the function '(\oplus)' defined below.

The function '(\otimes)' representing the pair congruence law is defined similarly.

REMARK 3. As an aside for the more theoretically minded reader, types and equivalence types form the objects and arrows of a category. The identity arrow is self and ' \diamond ' implements the composition of arrows. Furthermore, the sum type is a bifunctor in this category; its action on arrows is given by ' \oplus '. In fact, since each arrow ep has an inverse inv ep, every parametric data type including the arrow type can be turned into a covariant functor.

Given these prerequisites *unify* can be defined as follows.

$$\begin{array}{ll} unify' :: \forall \tau_{1} \ \tau_{2} . Rep \ \tau_{1} \rightarrow Rep \ \tau_{2} \rightarrow [\tau_{1} \leftrightarrow \tau_{2}] \\ unify' \left(R_{Int} \ ep_{1}\right) \left(R_{Int} \ ep_{2}\right) \\ &= \left[inv \ ep_{2} \diamond ep_{1}\right] \\ unify' \left(R_{1} \ ep_{1}\right) \left(R_{1} \ ep_{2}\right) \\ &= \left[inv \ ep_{2} \diamond ep_{1}\right] \\ unify' \left(R_{+} \ r_{\alpha_{1}} \ r_{\beta_{1}} \ ep_{1}\right) \left(R_{+} \ r_{\alpha_{2}} \ r_{\beta_{2}} \ ep_{2}\right) \\ &= \left[inv \ ep_{2} \diamond (ep_{\alpha} \oplus ep_{\beta}) \diamond ep_{1}\right] \\ ep_{\alpha} \leftarrow unify' \ r_{\alpha_{1}} \ r_{\alpha_{2}} \ ep_{\beta} \leftarrow unify' \ r_{\beta_{1}} \ r_{\beta_{2}}\right] \\ unify' \left(R_{\times} \ r_{\alpha_{1}} \ r_{\beta_{1}} \ ep_{1}\right) \left(R_{\times} \ r_{\alpha_{2}} \ r_{\beta_{2}} \ ep_{\beta} \diamond ep_{1}\right] \\ &= \left[inv \ ep_{2} \diamond (ep_{\alpha} \otimes ep_{\beta}) \diamond ep_{1}\right] \\ ep_{\alpha} \leftarrow unify' \ r_{\alpha_{1}} \ r_{\alpha_{2}} \ ep_{\beta} \leftarrow unify' \ r_{\beta_{1}} \ r_{\beta_{2}}\right] \\ unify' - = \left[\right] \\ unify' = \left[1\right] \\ unif$$

Using run-time unification we can easily cast a dynamic value into a static value of a given representable type.

$$\begin{array}{rcl} rCast & :: & \forall \tau . Rep \ \tau \to Dynamic \to \tau \\ rCast \ r_{\tau} \ (Dyn \ r_{\alpha} \ a) & = & \begin{array}{c} case \ unify \ r_{\tau} \ r_{\alpha} \ of \\ Just \ ep \to to \ ep \ a \\ Nothing \to \\ error \ "cast: \ type \ mismatch" \\ cast & :: & (Representable \ \tau) \Rightarrow Dynamic \to \tau \\ cast \ d & = & rCast \ rep \ d \end{array}$$

Another useful function is dynamic function application, the application of a dynamic function to a dynamic value. We introduce a new case R_{\rightarrow} similar to R_{+} and R_{\times} to *Rep*.

 $\begin{array}{rcl} apply & :: & Dynamic \rightarrow Dynamic \rightarrow Dynamic \\ apply (Dyn (R_{\rightarrow} r_{\alpha} r_{\beta} ep) f) (Dyn r_{\alpha'} x) \\ & = & \mathbf{case} \ unify r_{\alpha} r_{\alpha'} \ \mathbf{of} \\ & Just \ ep' \rightarrow Dyn \ r_{\beta} \left((from \ ep \ f) \ (to \ ep' \ x) \right) \\ & Nothing \rightarrow error "apply: type \ mismatch" \\ apply _ _ & = & error "apply: not a \ function" \end{array}$

EXAMPLE 1. Using dynamic values we can, for instance, implement a heterogeneous symbol table—a finite map from strings to values of any type.

For alternative solutions the reader is referred to Weirich [32]. \Box

EXAMPLE 2. Dynamic values also provide a simple way of implementing C's printf function in a type-safe manner; see also [27]. The printf function allows the programmer to show an arbitrary number of arguments of different types. Both the number of arguments and their types are specified by a so-called format string which is passed as a first argument to printf. Since the format string may be unknown at compile time (because it may be read from an external source), printf cannot be statically type-checked.

printf	::	$String \rightarrow [Dynamic] \rightarrow ShowS$
printf "" _	=	showString ""
printf('%':'d':cs)(d:ds)	=	shows (cast d::Int)
		• printf cs ds
printf('%':'s':cs)(d:ds)	=	showString (cast d :: String)
		\cdot printf cs ds
printf ('%':'%':cs) ds	=	showChar '%' · printf cs ds
printf('%':c:cs)[]	=	error "printf: missing "
		"argument"
printf $(c:cs)$ ds	=	showChar $c \cdot printf \ cs \ ds$

Note that the code assumes that the String type is representable. \Box

3.2 Closing the circle

We add *Dynamic* to the family of representable types, so that we can also pass a dynamic value to a polytypic function

data Rep
$$\tau = \dots$$

 $\mid R_{Dynamic} (\tau \leftrightarrow Dynamic)$

Note that *Rep* τ and *Dynamic* are now defined by mutual recursion.

Of course, we have to extend the polytypic function definitions to take the new case into account. Here is how we take equality of two dynamic values.

$$\begin{aligned} rEqual & (R_{Dynamic} \ ep) \ d_1 \ d_2 \\ = & \mathbf{case} \ (from \ ep \ d_1, from \ ep \ d_2) \ \mathbf{of} \\ & (Dyn \ r_{\alpha_1} \ a_1, Dyn \ r_{\alpha_2} \ a_2) \rightarrow \\ & \mathbf{case} \ unify \ r_{\alpha_1} \ r_{\alpha_2} \ \mathbf{of} \\ & Just \ ep' \rightarrow rEqual \ r_{\alpha_1} \ a_1 \ (to \ ep' \ a_2) \\ & Nothing \rightarrow False \end{aligned}$$

We first determine whether the types of the dynamic values are equal. If this is the case, *rEqual* is called recursively to check whether the values are equal, as well.

4 Generics

4.1 Generic representation types

What have we achieved so far? Using type representations we can program a function that works uniformly for all *representable* types. Let's become more ambitious now. We aim at broadening the scope of the polytypic functions so that they work for *all* types including types that the programmer is yet to define. We won't achieve this goal in its full glory—this requires an external tool or some support from the compiler—but we will get pretty close. The programmer only has to do a bit of extra work for each newly introduced type.

The principal idea is to make every type representable. Consider as a first simple example the data type of Booleans.

Now, the type *Bool* is isomorphic to the sum type 1 + 1, which is already representable.⁴ Here are functions that convert to and fro.

Using these isomorphisms we can represent the type *Bool* as follows.

$$r_{Bool}$$
 :: Rep Bool
 r_{Bool} = $R_+ r_1 r_1 (EP from_{Bool} to_{Bool})$

The type 1 + 1 is the so-called *generic representation type* of *Bool*, see [18].

Since Haskell's **data** construct introduces a sum of products and both sums and products are representable, it looks as if we are done. But not quite, data types may be recursively defined and they may be parametric (possibly abstracting over higher-order kinded type constructors). We will address each point in turn.

Haskell's list data type serves as a nice example for a data type that is both recursive and parametric.

data
$$[\alpha] = [] | \alpha : [\alpha]$$

Its generic representation type is $1+(\alpha\times[\alpha])$ with the isomorphisms given by

<i>from</i> []	::	$\forall \alpha . \left[\alpha \right] \to 1 + \left(\alpha \times \left[\alpha \right] \right)$
from[] []	=	Inl Unit
$from_{[]}^{\Box}(a:as)$	=	Inr (a ::: as)
to	::	$\forall \alpha . 1 + (\alpha \times [\alpha]) \rightarrow [\alpha]$
$to_{[]}$ (Inl Unit)	=	[]
$to_{[]}$ (Inr (a :×: as))	=	<i>a</i> : <i>as</i> .

Thus, the following representation of $[\alpha]$ suggests itself.

$$\begin{array}{rcl} r_{[]} & :: & \forall \alpha . \textit{Rep} \; \alpha \to \textit{Rep} \; [\alpha] \\ r_{[]} \; r_{\alpha} & = & R_{+} \; r_{1} \; (r_{\times} \; r_{\alpha} \; (r_{[]} \; r_{\alpha})) \; (\textit{EP from}_{[]} \; \textit{to}_{[]}) \end{array}$$

Two points are worth noting. First, the type representation of the list type constructor is a *function* taking a representation of

⁴Strictly speaking, the types *Bool* and 1 + 1 are not isomorphic in Haskell since 1 contains an additional bottom element. We simply ignore this complication here.

 τ to a representation of $[\tau]$. Second, the representation of $[\tau]$ is given by an *infinite* term as type recursion is mapped onto value recursion. Since Haskell is a lazy language, this is not a problem as far as the polytypic functions are concerned: the call *rEqual* $(r_{[]} r_{Int}) [0..8] [0..9]$, for instance, happily evaluates to *False*. However, the presence of infinite terms renders the unification of representations impossible: quite annoyingly the call *cast* (*dynamic* [0..9::Int]):::[*Int*] does not terminate.

There are at least two solutions to this problem. We could represent type recursion explicitly by introducing a fixed point operator—this is the approach taken in PolyP [19]. However, this is technically rather awkward and never completely general as type recursion may span over several types (mutual recursion) and as it may involve type constructors rather than types (so-called *nested data types*, see [6]). Thus, we would need an infinite family of fixed point operators. Furthermore, checking equality of higher-order kinded type constructors is undecidable. Haskell avoids the latter problem by using *name equivalence* rather than *structural equivalence*, which motivates the second solution.

We continue to represent recursive types by infinite terms but additionally label the representation by its Haskell name. The following data type is sufficient for capturing closed Haskell type terms (including higher-order kinded types).

For instance, [Int] is represented by App "[]" [App "Int" []]. We augment $Rep \tau$ by one additional constructor.

$$\begin{aligned} \text{data } Rep \ \tau &= & R_{Int} & (\tau \leftrightarrow Int) \\ & & R_{Dynamic} & (\tau \leftrightarrow Dynamic) \\ & & R_1 & (\tau \leftrightarrow 1) \\ & & \forall \alpha \ \beta . R_+ (Rep \ \alpha) (Rep \ \beta) (\tau \leftrightarrow (\alpha + \beta)) \\ & & \forall \alpha \ \beta . R_\times (Rep \ \alpha) (Rep \ \beta) (\tau \leftrightarrow (\alpha \times \beta)) \\ & & \forall \alpha \ . R_{Type} \ Term (Rep \ \alpha) (\tau \leftrightarrow \alpha) \end{aligned}$$

On the face of it, we now have two types for type representations: Rep τ captures the structural information and Term captures the naming information. The function term_{*} extracts the latter information from the former.

$$term_{\star} :: \quad \forall \tau . Rep \ \tau \to Term$$

$$term_{\star} (R_{Int} \ ep) = App \ "Int" []$$

$$term_{\star} (R_{Dynamic} \ ep) = App \ "Dynamic" []$$

$$term_{\star} (R_{1} \ ep) = App \ "1" []$$

$$term_{\star} (R_{+} \ r_{\alpha} \ r_{\beta} \ ep) = App \ "(+)" \ [term_{\star} \ r_{\alpha}, term_{\star} \ r_{\beta}$$

$$term_{\star} (R_{\times} \ r_{\alpha} \ r_{\beta} \ ep) = t$$

We change the definition of $r_{[]}$ to incorporate the list type name.

$$\begin{array}{lll} r_{[]} & :: & \forall \alpha . \operatorname{Rep} \alpha \to \operatorname{Rep} [\alpha] \\ r_{[]} r_{\alpha} & = & \operatorname{R}_{\operatorname{Type}} (\operatorname{App} "[]" [\operatorname{term}_{\star} r_{\alpha}]) \\ & & (r_{+} r_{1} (r_{\times} r_{\alpha} (r_{[]} r_{\alpha}))) (\operatorname{EP} \operatorname{from}_{[]} to_{[]}) \end{array}$$

It remains to extend the definition of *unify*'. To unify two labelled representations $R_{Type} t_1 r_{\alpha_1} ep_1$ and $R_{Type} t_2 r_{\alpha_2} ep_2$, we simply test t_1 and t_2 for equality.

$$unify' (R_{Type} t_1 r_{\alpha_1} ep_1) (R_{Type} t_2 r_{\alpha_2} ep_2) = [inv ep_2 \diamond head (unify' r_{\alpha_1} r_{\alpha_2}) \diamond ep_1 | t_1 == t_2]$$

If t_1 and t_2 are equal, we know that r_{α_1} and r_{α_2} must be unifiable. The call *head* (*unify'* r_{α_1} r_{α_2}) immediately returns the proof. Note that the following definition of unify' does not work, as it is too eager.

$$\begin{array}{l} \operatorname{unify'} \left(R_{Type} t_1 r_{\alpha_1} ep_1 \right) \left(R_{Type} t_2 r_{\alpha_2} ep_2 \right) & -- \text{WRONG} \\ = & \left[\operatorname{inv} ep_2 \diamond ep_\alpha \diamond ep_1 \right| t_1 == t_2, ep_\alpha \leftarrow \operatorname{unify'} r_{\alpha_1} r_{\alpha_2} \right] \end{array}$$

Turning to the treatment of higher-order kinded data types let us first take a look at one popular example. The following definition introduces so-called *generalized rose trees*.

data Tree
$$\phi \alpha$$
 = Node $\alpha (\phi (Tree \phi \alpha))$

Since the first argument of *Tree* ranges over type constructors of kind $\star \rightarrow \star$, *Tree* has kind $(\star \rightarrow \star) \rightarrow \star \rightarrow \star$. We have already seen that a type constructor ϕ of kind $\star \rightarrow \star$ is represented by a function of type $\forall \alpha$. *Rep* $\alpha \rightarrow Rep$ ($\phi \alpha$). Since *Tree* abstracts over type constructors of this kind it has type

$$\begin{array}{rcc} r_{Tree} & :: & \forall \phi . (\forall \alpha . Rep \ \alpha \rightarrow Rep \ (\phi \ \alpha)) \rightarrow \\ & (\forall \alpha . Rep \ \alpha \rightarrow Rep \ (Tree \ \phi \ \alpha)). \end{array}$$

Note that r_{Tree} possesses a so-called rank-2 type. In general, a type constructor τ of kind κ is represented by an element of $Rep_{\kappa} \tau$ with

$$\begin{array}{rcl} \operatorname{Rep}_{\star} \tau & = & \operatorname{Rep} \tau \\ \operatorname{Rep}_{\kappa_{1} \to \kappa_{2}} \tau & = & \forall \alpha \, . \, \operatorname{Rep}_{\kappa_{1}} \alpha \to \operatorname{Rep}_{\kappa_{2}} (\tau \alpha) \end{array}$$

As the latest version of the Glasgow Haskell compiler (GHC 5.03) supports rank-*n* types, we can, in fact, represent types of arbitrary kinds.

So far so good. One small problem remains though. To define the representation of *Tree* $\phi \alpha$, we have to construct type terms from the representations of ϕ and α . Since the representation of ϕ of type $Rep_{\star\to\star} \phi$ is a *function* this sounds like a hard nut to crack. Fortunately, Haskell's type language is a multi-sorted term algebra as Haskell does not offer general type abstraction. Each type term is of the form *App s* $[t_1, \ldots, t_n]$; type application is purely syntactic: applying *App s* $[t_1, \ldots, t_n]$ to *t* yields *App s* $[t_1, \ldots, t_n, t]$. Consequently, from the result of an application we can reconstruct both the original function and its argument.

$$term_{\star \to \star} :: \quad \forall \phi. (\forall \alpha. Rep \ \alpha \to Rep \ (\phi \ \alpha)) \to Term$$
$$term_{\star \to \star} r_{\phi} = case \ term_{\star} \ (r_{\phi} \ r_{1}) \ of \ App \ t \ ts \to App \ t \ (init \ ts)$$

Given these prerequisites we define

$$\begin{array}{rcl} r_{Tree} r_{\phi} r_{\alpha} & = & R_{Type} \left(App \ ^{"} \text{Tree"} \\ & & \left[term_{\star \to \star} r_{\phi}, term_{\star} r_{\alpha} \right] \right) \\ & \left(r_{\times} r_{\alpha} \left(r_{\phi} \left(r_{Tree} r_{\phi} r_{\alpha} \right) \right) \right) \\ & \left(EP \ from_{Tree} to_{Tree} \right) \\ from_{Tree} \left(Node \ a \ ts \right) & = & \left(a : \times : ts \right) \\ to_{Tree} & & :: & \forall \phi \ \alpha . \ \alpha \times (\phi \left(Tree \ \phi \ \alpha \right) \right) \to Tree \ \phi \ \alpha \\ to_{Tree} \left(a : \times : ts \right) & = & Node \ a \ ts \end{array}$$

4.2 Constructor names

To be able to write polytypic functions that show or read elements of some data type, we add one more constructor to the *Rep* data type.

data
$$Rep \tau = \dots$$

 $| R_{Con} String (Rep \tau)$

The R_{Con} constructor is intended to record the string representation of a data constructor. Of course, in practice one would replace *String* by a more elaborate data type that contains further information such as fixity, see [18]. The updated definition of r_{Bool} illustrates the use of R_{Con} .

$$\begin{array}{lll} r_{Bool} & :: & Rep \ Bool \\ r_{Bool} & = & R_{Type} \ (App \ "Bool" \ []) \\ & & (r_+ \ (R_{Con} \ "False" \ r_1) \ (R_{Con} \ "True" \ r_1)) \\ & & (EP \ from_{Bool} \ to_{Bool}) \end{array}$$

Here is a simplified version of Haskell's *show* function, which converts an element of any data type to its string representation. To understand the definition keep in mind that the sum type is used to represent the cases of a **data** declaration while the product type is used to represent the arguments of a single constructor. The unit type 1 signals that a constructor has no arguments.

::	$\forall \tau . Rep \ \tau \rightarrow \tau \rightarrow ShowS$
=	shows (from $ep t$)
=	case from ep t of
	$Dyn r_{\alpha} x \rightarrow$
	showChar ' ('
	 showString "dynamic "
	\cdot rShows $r_{\alpha} x$
	\cdot showChar ') '
=	showString " "
=	case from ep t of
	Inl $a \rightarrow rShows r_{\alpha} a$
	Inr $b \rightarrow rShows r_{\beta} b$
=	case from ep t of
	$(a:::b) \rightarrow$
	rShows r_{α} a
	 showString " "
	\cdot rShows $r_{\beta} b$
=	rShows r_{α} (from ep t)
=	showString s
	nullary constructor
=	showChar ' (' · showString s
	\cdot showChar ' ' \cdot rShows r_{α} t
	· showChar ') '

Since type representations are ordinary values, we can separate special cases simply by pattern matching. The second but last equation of *rShows*, for instance, handles nullary constructors while the last equation takes care of the remaining cases.

5 Related work

The polymorphic Horn clause language of Hanus [12] generalizes the untyped Horn clause resolution semantics of Prolog to typed and polymorphically typed terms. Our initial definition of *Rep* in Section 2.1 is legal in this language, which appears to be strictly more powerful than Haskell. Interestingly, the semantics requires the presence of types at run time. Optimizations are possible for so-called *type preserving* functions where the type variables of the argument types also occur in the result type (note that the *Rep* constructors are type-preserving).

Jansson and Jeuring [19] developed PolyP, a variant of Haskell that includes a polytypic function construct permitting definitions by primitive recursion on the structure of regular data types, but did not support higher-order kinded type arguments. Hinze [17] proposed an approach based on indexing values by types and types by kinds. This made it possible to write definitions of functions like *map* that work for arbitrary polymorphic data structures. This approach has been implemented in Generic Haskell [7], a successor to PolyP. Hinze and Peyton Jones [18] introduced derivable type classes, which can define type-indexed values within classes but are limited to kind \star . Clean's generics system [3] generalizes derivable type classes to allow generic type classes defined at arbitrary kinds rather than just \star .

Abadi et al. [2] first considered rigorously the problem of adding a *Dynamic* type and type pattern matching *typecase* to a monomorphic ML-like language. Leroy and Mauny [21] studied the interaction of *Dynamic* with implicit polymorphism and implemented a restricted form of polymorphic type pattern matching with both \forall and \exists quantifiers. Abadi et al. [1] considered dynamics with explicit and implicit polymorphism, and showed how to generalize *typecase* to arbitrary polymorphic patterns. We believe our *Dynamic* also can support making values of closed polymorphic types dynamic, although we have yet to experiment with unifying and pattern-matching polymorphic type representations.

GHC's *Dynamic* library contains *TypeRep* and *Dynamic* types and a *Typeable* class that are weaker, 'untyped' versions of our *Dynamic*, *Rep*, and *Representable*. Type representations are abstract, and it is impossible to, for example, unpack component *TypeReps* from a product *TypeRep*. On the other hand, our typed versions constitute a safe implementation of these constructs.

Clean also includes support in development for a richer type *Dynamic* [26] that includes *typecase* with pattern matching on (possibly polymorphic) types, in the style of Leroy and Mauny, and also supports type-dependent functions. Clean's dynamics employ a type class $TC \alpha$ that says that it is possible to make α dynamic, so, unlike earlier approaches, values with partially abstract types containing free type variables can be cast to *Dynamic* as long as all the type variables are of class *TC*. Our *Dynamic* supports exactly this behaviour, whence Clean's *TC* is analogous to our *Representable* class.

Shields, Sheard, and Peyton Jones [27] present an alternative implementation of dynamics based on staged type inference. In staged computation [10, 28], compilation of parts of a program may be delayed, so functions may be specialized to arguments available at compile time. Staged type inference delays type inference and type checking until run time as well. This makes it possible to avoid many of the difficulties of explicit polymorphic type pattern matching encountered in previous approaches, since unification occurs at run time when concrete type information is available. Our approach also employs run-time unification, if only for monomorphic types, but our *unify* is a user-level program rather than compilergenerated code. It would be interesting to see whether our approach generalizes to polymorphic unifcation. Staged computation may also be useful in optimizing representation-passing by specializing generic functions to particular representations. We have also experimented with using GHC's rewrite rules [24] to automatically rewrite representation-based functions when type information is known at compile time. We found that functions can be fully specialized to non-recursive types, but not to recursive types like [] because recursive types are represented by recursively defined representations. As a result, rewrite rules in their present form are of limited use for optimizing representation-based programs.

Weirich [32] showed how to implement type-safe cast and a form of *Dynamic* in Haskell using type classes. The two Haskell implementations of *cast* employ mutually recursive type classes *CastTo* α and *CastFrom* β ; the first implementation of these classes interprets cast as coercion ($\alpha \rightarrow \beta$), whereas the second interprets cast as unrestricted substitution ($\phi \alpha \rightarrow \phi \beta$). These interpretations of cast correspond exactly to our interpretations of type equivalence.

Implicit, compiler-generated type information has been studied in many languages and proposals for implementing statically-typed dynamics and implementing intensional polymorphism. Explicit type representations are not new either: they were introduced by Crary, Weirich, and Morrisett [9]; the authors also observed that representations could be used to implement an explicit *Dynamic* type. Crary and Weirich [8] and Weirich [33] have also considered encodings of type representations in the more powerful type systems LX, which includes function, sum, product, and recursive kinds, and LU^- , which includes impredicative kind polymorphism.

Baars and Swierstra [4] have independently discovered the type representation encoding presented in Section 2. However, instead of starting with representation-passing generic functions and attempting to implement representations, they start with dynamic types and postulate a type family *TypeRep* α that contains enough information for dynamic typechecking, and then derive an implementation for it. Baars and Swierstra address dynamic typing issues beyond those considered here, such as dynamic typing and compilation of expressions. In contrast, we have considered both generics and dynamics, and interrelated them. We have also shown how to represent a more general class of types, including polymorphic and recursive types.

6 Conclusions

Previous approaches to implementing generic programming and dynamic typing in high-level statically typed languages have involved substantial language modifications and substantial proofs of type safety for the modified language. Dynamics and generics have been studied separately, leaving unresolved the question of whether dynamic values can be used with generic functions and vice versa. We have shown that generic programming and dynamic typing features can be derived simultaneously and compatibly from type representations. Moreover, type representations can be encoded in Haskell using existentials and equivalence types, so they can be implemented and given a semantics by translation. As far as we know this is the first approach to make this connection between statically typed generics and dynamics explicit.

Unlike prior approaches to implementing type representations, we encode representations as ordinary data types and *typecases* as ordinary cases. As a result, all of the existing pattern matching constructs and optimizations carry over to representation patterns with no effort. Mutually recursive functions and multiple type arguments also pose no problems. Representation-passing functions can be compiled separately from their calling contexts; in contrast, other approaches to statically typed generic programming cannot compile generic function uses and definitions separately. Dynamic types and run-time type checking can be defined in terms of representations, but since type representations are explicitly typed program data, this implementation of *Dynamic* is more flexible than implementations in which type information is compiler-generated and abstract.

There are several directions for improving our approach. For example, it is not possible to override the behaviour of a polytypic function at some specific instance (without changing the definition of *Rep*). In contrast, overriding is easy using type classes. Extensible data types might alleviate this problem. Our encoding also incurs unnecessary run-time type dispatch overhead when types are available at compile time. Furthermore, our encoding translates arbitrary tuples and data types to a universal data type consisting of binary products, sums, and constructors, which may incur additional over-

head. These drawbacks could be addressed through specialization, run-time code generation, or deforestation optimizations. Our encoding requires a fair amount of programmer effort, and we plan to address this by implementing extensions such as **with** clauses in Haskell via translation. Finally, while it is possible to define polytypic functions such as *map* that analyze type constructors of kind other than \star (using a different *Rep* type), constructing functions that work for all types of all kinds seems out of reach within Haskell's type system. These are all important directions for future work.

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A Listing

A.1 Generic representation types

$$\begin{array}{rcl} \mbox{data } 1 & = & Unit \\ \mbox{data } \alpha + \beta & = & Inl \ \alpha \ | \ Inr \ \beta \\ \mbox{data } \alpha \times \beta & = & \alpha : \times : \beta \end{array}$$

Standard mapping functions on the above types (and on the function type).

$$\begin{array}{lll} (+) & :: & \forall \alpha \beta . (\alpha \to \beta) \to (\forall \gamma \delta . (\gamma \to \delta) \to ((\alpha + \gamma) \to (\beta + \delta))) \\ (f + g) (Inl a) & = & Inl (f a) \\ (f + g) (Inr b) & = & Inr (g b) \\ (\times) & :: & \forall \alpha \beta . (\alpha \to \beta) \to (\forall \gamma \delta . (\gamma \to \delta) \to ((\alpha \times \gamma) \to (\beta \times \delta))) \\ (f \times g) (a : \times : b) & = & f a : \times : g b \\ (\to) & :: & \forall \alpha \beta . (\alpha \to \beta) \to (\forall \gamma \delta . (\gamma \to \delta) \to ((\beta \to \gamma) \to (\alpha \to \delta))) \\ (f \to g) h & = & g \cdot h \cdot f \end{array}$$

A.2 Type equivalence

data
$$\alpha \leftrightarrow \beta = EP\{from :: \alpha \rightarrow \beta, to :: \beta \rightarrow \alpha\}$$

Reflexivity, symmetry and transitivity.

$$\begin{array}{rcl} self & :: & \forall \alpha . \alpha \leftrightarrow \alpha \\ self & = & EP\{from = id, to = id\} \\ inv & :: & \forall \alpha \beta . (\alpha \leftrightarrow \beta) \rightarrow (\beta \leftrightarrow \alpha) \\ invf & = & EP\{from = to f, to = from f\} \\ \textbf{infixr } 9 \diamond \\ (\diamond) & :: & \forall \alpha \beta \gamma . (\beta \leftrightarrow \gamma) \rightarrow (\alpha \leftrightarrow \beta) \rightarrow (\alpha \leftrightarrow \gamma) \\ f \diamond g & = & EP\{from = from f \cdot from g, to = to g \cdot to f\} \end{array}$$

Mapping functions for generic representation types (and for the function type) implementing the laws of congruence.

A.3 Type representations

Smart constructors.

r _{Int}	::	Rep Int
r _{Int}	=	R _{Int} self
r _{Char}	::	Rep Char
r _{Char}	=	R _{Char} self
r _{Dynamic}	::	Rep Dynamic
r _{Dynamic}	=	R _{Dynamic} self
r_{\rightarrow}	::	$\forall \alpha. \operatorname{Rep} \alpha \rightarrow (\forall \beta. \operatorname{Rep} \beta \rightarrow \operatorname{Rep} (\alpha \rightarrow \beta))$
$r_{\rightarrow} r_{\alpha} r_{\beta}$	=	$R_{\rightarrow} r_{\alpha} r_{\beta} self$
r_1	::	Rep 1
r_1	=	R_1 self
r_+	::	$\forall \alpha . \operatorname{Rep} \alpha \rightarrow (\forall \beta . \operatorname{Rep} \beta \rightarrow \operatorname{Rep} (\alpha + \beta))$
$r_+ r_{\alpha} r_{\beta}$	=	$R_+ r_{\alpha} r_{\beta} self$
r×	::	$\forall \alpha . Rep \ \alpha \rightarrow (\forall \beta . Rep \ \beta \rightarrow Rep \ (\alpha \times \beta))$
$r_{\times} r_{\alpha} r_{\beta}$	=	$R_{\times} r_{\alpha} r_{\beta} self$

A class for representable types.

class Representable τ where rep :: Rep τ instance Representable Int where rep = r_{Int} instance Representable Char where rep = r_{Char} instance Representable Dynamic where rep = $r_{Dynamic}$ instance (Representable a, Representable b) \Rightarrow Representable $(a \rightarrow b)$ where rep = r_{\rightarrow} rep rep instance (Representable α , Representable β) \Rightarrow Representable $(\alpha + \beta)$ where rep = r_{+} rep rep instance (Representable α , Representable β) \Rightarrow Representable $(\alpha + \beta)$ where rep = r_{+} rep rep instance (Representable α , Representable β) \Rightarrow Representable $(\alpha \times \beta)$ where rep = r_{\times} rep rep

A.4 Dynamics

 $\begin{array}{lll} \textbf{data } Dynamic &=& \forall \alpha. Dyn \ (Rep \ \alpha) \ \alpha \\ dynamic & :: & \forall \alpha. \ (Representable \ \alpha) \Rightarrow \alpha \rightarrow Dynamic \\ dynamic \ x & = & Dyn \ rep \ x \end{array}$

Run-time unification of types.

Type-safe cast and dynamic function application.

rCast	::	$\forall \tau. Rep \ \tau \rightarrow Dynamic \rightarrow \tau$
<i>rCast</i> r_{τ} (<i>Dyn</i> r_{α} <i>a</i>)	=	case unify $r_{\tau} r_{\alpha}$ of
		Just $ep \rightarrow to ep a$
		Nothing ightarrow error "cast: type mismatch"
cast	::	$(Representable \ \tau) \Rightarrow Dynamic \rightarrow \tau$
cast d	=	rCast rep d
apply		$Dynamic \rightarrow Dynamic \rightarrow Dynamic$
apply (Dyn ($R_{\rightarrow} r_{\alpha} r_{\beta}$	3 ep)	$f) (Dyn r_{\alpha'} x)$
	=	case unify $r_{\alpha} r_{\alpha'}$ of
		Just $ep' \rightarrow Dyn r_{\beta} ((from ep f) (to ep' x))$
		$Nothing \rightarrow error$ "apply: type mismatch"
$apply _ _$	=	error "apply: not a function"

A.5 Type terms

data Term	=	App String [Term] deriving (Show, Eq)
term _*	::	$\forall \tau . Rep \ \tau \rightarrow Term$
$term_{\star} (R_{Int} ep)$	=	<i>App</i> "Int" []
$term_{\star} (R_{Char} ep)$	=	<i>App</i> "Char" []
$term_{\star} (R_{Dynamic} ep)$	=	App "Dynamic" []
$term_{\star} (R_{\rightarrow} r_{\alpha} r_{\beta} ep)$	=	App "->" [term r_{α} , term r_{β}]
$term_{\star} (R_1 ep)$	=	App "1" []
$term_{\star} (R_{+} r_{\alpha} r_{\beta} ep)$	=	App "(+)" [$term_{\star} r_{\alpha}, term_{\star} r_{\beta}$]
$term_{\star} (R_{\times} r_{\alpha} r_{\beta} ep)$	=	App "(*)" [$term_{\star} r_{\alpha}, term_{\star} r_{\beta}$]
$term_{\star} (R_{Type} \ t \ r_{\alpha} \ ep)$	=	t
$term_{\star \to \star}$::	$\forall \phi . (\forall \alpha . \operatorname{Rep} \alpha \rightarrow \operatorname{Rep} (\phi \alpha)) \rightarrow \operatorname{Term}$
$term_{\star \to \star} r_{\phi}$	=	case $term_{\star}$ $(r_{\phi} r_1)$ of App t $ts \rightarrow App t$ (init ts)

A.6 Generics

Examples of type representations.

Examples of type represent	tions.	
		$= R_{Type} (App "Bool" []) (r_+ (R_{Con} "False" r_1) (R_{Con} "True" r_1)) (EP from_{Bool} to_{Bool})$
	$\begin{array}{ll} \textit{from}_{Bool} & :: \\ \textit{from}_{Bool} \textit{ False} & = \\ \textit{from}_{Bool} \textit{ True} & = \end{array}$	= Inl Unit
	<i>D001</i> (, , , ,)	$= False$ $= True$ $: \forall \alpha. Rep \ \alpha \rightarrow Rep \ [\alpha]$
	to _[] to _[] (I	
	rep = instance	$\begin{array}{l} Representable \ Bool \ \textbf{where} \\ = & r_{Bool} \\ r(Representable \ \alpha) \Rightarrow Representable \ [\alpha] \ \textbf{where} \\ = & r_{[]} \ rep \end{array}$
Generic functions: generic e		
	rEqual	$:: \forall \tau. \operatorname{Rep} \tau \to \tau \to \tau \to \operatorname{Bool}$
	rEqual $(R_{Int} ep) t_1 t_2$ rEqual $(R_{Char} ep) t_1$ rEqual $(R_{Dynamic} ep)$	$\begin{array}{rcl} & = & from \ ep \ t_1 == from \ ep \ t_2 \\ t_2 & = & from \ ep \ t_1 == from \ ep \ t_2 \end{array}$
	$rEqual (R_{\rightarrow} r_{\alpha} r_{\beta} ep)$ $rEqual (R_1 ep) t_1 t_2$	$ \begin{array}{llllllllllllllllllllllllllllllllllll$
	<i>rEqual</i> ($R_+ r_{\alpha} r_{\beta} ep$)	
	<i>rEqual</i> ($R_{\times} r_{\alpha} r_{\beta} ep$)	$) t_1 t_2 = \operatorname{case} (from ep t_1, from ep t_2) \operatorname{of} (a_1 ::: b_1, a_2 ::: b_2) \rightarrow rEqual r_{\alpha} a_1 a_2 \wedge rEqual r_{\beta} b_1 b_2$
	$ rEqual (R_{Type} e r_{\alpha} ep r_{\alpha} ep r_{\alpha}) t_{1} $	p) $t_1 t_2 = rEqual r_{\alpha}$ (from $ep t_1$) (from $ep t_2$)
Generic minimum.		
	rMinBound $rMinBound$ (R_{Int} $rMinBound$ (R_{Cha} $rMinBound$ (R_{Dyn} $rMinBound$ (R_{\rightarrow} $rMinBound$ (R_{+} $rMinBound$ (R_{+} $rMinBound$ (R_{X}) $rMinBound$ (R_{Typ} $rMinBound$ (R_{Con}	$\begin{array}{llllllllllllllllllllllllllllllllllll$

Generic unparsing.

Generic memoization.

rShows	::	$\forall \tau . Rep \ \tau \rightarrow \tau \rightarrow ShowS$		
rShows $(R_{Int} ep) t$	=	shows (from ep t)		
rShows $(R_{Char} ep) t$	=	shows (from ep t)		
$rShows$ ($R_{Dynamic} ep$) t	=	case from ep t of		
		Dyn $r_{\alpha} x \rightarrow showChar$ '(' · showString "dynamic "		
		\cdot rShows $r_{\alpha} x \cdot$ showChar ')'		
<i>rShows</i> $(R_{\rightarrow} r_{\alpha} r_{\beta} ep) t$	=	<pre>showString "<function>"</function></pre>		
rShows $(R_1 ep) t$	=	showString ""		
rShows $(R_+ r_{\alpha} r_{\beta} ep) t$	=	case from ep t of		
() p - /		Inl $a \rightarrow rShows r_{\alpha} a$		
		Inr $b \rightarrow rShows r_{\beta} b$		
<i>rShows</i> $(R_{\times} r_{\alpha} r_{\beta} ep) t$	=	case from ep t of		
		$(a:\times:b) \rightarrow rShows r_{\alpha} a \cdot showString " " \cdot rShows r_{\beta} b$		
rShows $(R_{Type} e r_{\alpha} ep) t$	=	rShows r_{α} (from ep t)		
rShows $(R_{Con} s (R_1 ep)) t$	=	showString s		
rShows $(R_{Con} \ s \ r_{\alpha}) \ t$	=	showChar' (' · showString s · showChar' '		
		\cdot rShows r_{α} t \cdot showChar ') '		
rMemo		$orall au \cdot Rep \ au ightarrow (au ightarrow u) ightarrow (au ightarrow u)$		
$rMemo(R_{Int} ep)f$		$\lambda t \rightarrow f t$ no memoization		
$rMemo\left(R_{Char} ep\right)f$	=	$\lambda t \rightarrow f t$ no memoization		
$rMemo\left(R_{Dynamic} ep\right) f$	=	$\lambda t \rightarrow f t$ no memoization		
<i>rMemo</i> $(R_{\rightarrow} r_{\alpha} r_{\beta} ep) f$	=	$\lambda t \rightarrow f t$ no memoization		
rMemo $(R_1 ep) f$	=	$\lambda t \rightarrow \mathbf{case} from \ ep \ t \ \mathbf{of}$		
		$Unit \rightarrow fUnit$		
where <i>fUnit</i>		f(to ep(Unit))		
<i>rMemo</i> $(R_+ r_{\alpha} r_{\beta} ep) f$	=	$\lambda t \rightarrow \mathbf{case} \ from \ ep \ t \ \mathbf{of}$		
		$Inl a \longrightarrow fInl a$		

Inl $a \rightarrow fInl a$

Note that we do not memoize primitive types such as Ints or Chars (this would require building a look-up table).